



Protection against accidental operation

Operating magnet protected against dirt and humidity

Application:

The valves are used for water or oil hydraulic control systems. They can also be used as pilot-control valves.

Technical data:

Type:

Direct controlled ball seat valve

Connections:

Plate mounting with O-ring seal on request available with connection plate
Connection thread
NW3 = R1/4" or 1/4" NPT
NW6 = R3/8" or 3/8" NPT

Medium:

Compressed air and gases

Viscosity:

1 to 300 cSt

Ambient temperature:

Depends on control element, see table "Technical data of control elements", higher temperatures on request

Seals:

NBR, other seal materials available upon request

Sealing:

Ball on seat

Pressure range:

0 to 100 bar for 3/2 dir.:

The pressure in connection "R" must not exceed 50% of working pressure

2

2/2 directional control seat valve 3/2 directional control seat valve NW3 and NW6 for gases

max. 100 bar for plate mounting

Operating elements can each be rotated through 90° Wear parts are easily accessible and can be replaced quickly

Switching time:

Depends on operating pressure and operating temperature (see table: technical data of control elements)

Fitted pos.:

Any

Flow direction:

2/2W: From "P" to "A"

3/2W: From "P" to "A" or from "A" to "R"

The connections "P", "A", and "R" must not be mixed up

Kv value:

NW 6: 6,5 l/min. NW 3: 1,2 l/min.

Materials:

All parts coming into contact with the flow medium are made of corrosion resistant materials

Operating modes:

Electric, hydraulic, pneumatic, mechanical or manual operation

Special features:

The valve is characterized by fast response times. The solenoid plunger of the electromagnet is dual-supported and thus protected against wear. By means of a diaphragm seal between the pushrod and the solenoid plunger chamber the control electromagnet is protected against dirt and humidity. The arrestable manual operation device can be accessed by removing the type plate and is thus also protected against any accidental operation. The electric magnet and all other control elements can each be rotated through 90°. All wear parts are easily accessible and quick to replace



Valve version "positive"

(Valve is closed when magnet is de-energized)

Fig. 1 (electromagnet de-energized):

The pressure spring (2) presses the valve ball (4) via pushrod (3) into the valve seat (5). The pressure of the medium in infeed "P" supports the pressure spring action (2). Thus the passage from infeed "P" to working line "A"is blocked.

Fig. 2 (electromagnet energized):

When the electromagnet (1) is switched on, the solenoid plunger (6) presses the valve ball (4) - via lever (7) and pushrod (8), and against the force of the pressure spring (2) and the pressure of the medium in the infeed "P" - from its valve seat (5). Now the passage from infeed "P" to working line "A" is clear.

Valve version "negative"

(Valve is open when magnet is de-energized)

Fig. 1 (electromagnet de-energized):

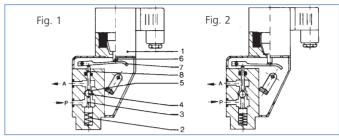
The pressure spring (2) lifts the valve ball (4) via pushrod (3) from the valve seat (5). Thus the passage from infeed "P" to working line "A" is clear.

Fig. 2 (electromagnet energized):

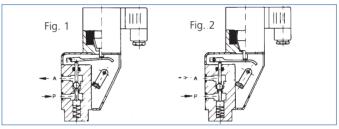
When the electromagnet (1) is switched on, the solenoid plunger (6) presses the valve ball (4) - via lever (7) and pushrod (8), and against the force of the pressure spring (2) and the pressure of the medium in the infeed "P" - into the valve seat (5). Now the passage from infeed "P" to working line "A" is blocked.

Type and Order example:			
Operating modes	Symbol	Type: NW 3	
Electromagnetic Example for 24 volts	w[]]z	2/2 KSV-03P-20NBNNN-ED024 2/2 KSV-03N-20NBNNN-ED024	*
Hydraulic	w[]]	2/2KSV-03P-20NBGNN-Z320 2/2KSV-03N-20NBGNN-Z320	*
Pneumatic	W	2/2 KSV-03P-20NBGNN-Z064 2/2 KSV-03N-20NBGNN-Z064	*
Mechanical (roller)	w[]=o	2/2KSV-03P-20NBGNN-RO 2/2KSV-03N-20NBGNN-RO	*
Manual	wije	2/2KSV-03P-20NBGNN-MAN 2/2KSV-03N-20NBGNN-MAN	*
		Type: NW 6	
Electromagnetic Example for 24 volts	w[]]z	2/2 KSV-06P-20NBNNN-ED024 2/2 KSV-06N-20NBNNN-ED024	*
Hydraulic	w[]]	2/2KSV-06P-20NBGNN-Z320 2/2KSV-06N-20NBGNN-Z320	*
Pneumatic	W	2/2 KSV-06P-20NBGNN-Z064 2/2 KSV-06N-20NBGNN-Z064	*
Mechanical (roller)	WIID	2/2KSV-06P-20NBGNN-RO 2/2KSV-06N-20NBGNN-RO	*
Manual	wij	2/2KSV-06P-20NBGNN-MAN 2/2KSV-06N-20NBGNN-MAN	*

electromagnet de-energized electromagnet energized

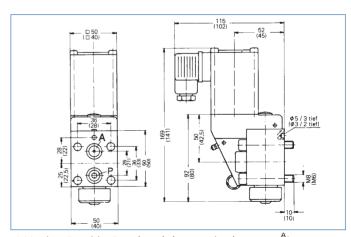


Д	working line	4	valve ball
В	infeed	5	valve seat
1	electromagnet	6	solenoid plunger
2	pressure spring	7	lever
3	pushrod	8	pushrod



Α	working line	4	valve ball
В	infeed	5	valve seat
1	electromagnet	6	solenoid plunger
2	pressure spring	7	lever
3	pushrod	8	pushrod

dimensional drawing dimensions shown outside brackets DN 6 dimensions shown in brackets DN 3



* Version "positive" = closed de-energized

** Version " = open de-energized



	NW3 infeed + working line	NW6 infeed + working line		
connection bore	3 mm	6 mm		
O-ring	0 25*1 78	10*7 5		



Valve version "positive"

(Valve passage from "P" to "A" is closed when magnet is deenergized)

Fig. 1 (electromagnet de-energized):

The medium fed in via infeed "P" presses the valve ball (4) into the valve seat (5), supported by the pressure spring (2). Thus the passage from infeed "P" to working line "A" is blocked.

Fig. 2 (electromagnet energized):

When the electromagnet (1) is switched on, the solenoid plunger (8) presses the valve ball (6) - via lever (9) and pushrod (10), and against the force of the pressure spring (2) - into the valve seat (7). Now drain "R" is blocked. At the same time, using the spacer pin (3), the valve ball (4) is pressed out of the valve seat (5), so that the passage from infeed "P" to working line "A" is now clear.

Valve version "negative"

(Valve passage from "P" to "A" is open when the magnet is deenergized) fig. 1 (electromagnet de-energized)

The pressure spring (2) lifts the valve ball (4) via pushrod (11) into valve seat (5). The medium flowing from infeed "P" to the working line supports the pressure spring action. Thus the drain "R" is blocked and the infeed "P" is connected to the working line "A".

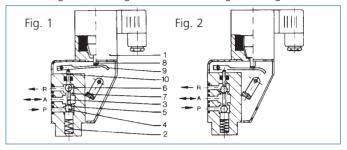
Fig. 2 (electromagnet energized)

When the electromagnet (1) is switched on, the solenoid plunger (8) presses the valve ball (4) - via lever (9) and pushrod (10), and against the force of the pressure spring (2) and the pressure of the medium in the infeed "P" - into the valve seat (7). Now the infeed "P" is blocked and the working line "A" is connected to drain "R".

Type and Order example:			
Operating modes	Symbol	Type: NW 3	
Electromagnetic Example for 24 volts	w[]]z	3/2KSV-03P-20NBNNN-ED024 3/2KSV-03N-20NBNNN-ED024	*
Hydraulic	WIII	3/2KSV-03P-20NBGNN-Z320 3/2KSV-03N-20NBGNN-Z320	*
Pneumatic	WII	3/2 KSV-03P-20NBGNN-Z064 3/2 KSV-03N-20NBGNN-Z064	*
Mechanical (roller)	w[]=o	3/2KSV-03P-20NBGNN-RO 3/2KSV-03N-20NBGNN-RO	*
Manual	WII	3/2KSV-03P-20NBGNN-MAN 3/2KSV-03N-20NBGNN-MAN	*
		Type: NW 6	
Electromagnetic Example for 24 volts	w[]]z	3/2KSV-06P-20NBNNN-ED024 3/2KSV-06N-20NBNNN-ED024	*
Hydraulic	w	3/2KSV-06P-20NBGNN-Z320 3/2KSV-06N-20NBGNN-Z320	*
Pneumatic	WIII	3/2 KSV-06P-20NBGNN-Z064 3/2 KSV-06N-20NBGNN-Z064	*
Mechanical (roller)	w[]=o	3/2KSV-06P-20NBGNN-RO 3/2KSV-06N-20NBGNN-RO	*
Manual	w[]	3/2KSV-06P-20NBGNN-MAN 3/2KSV-06N-20NBGNN-MAN	*

electromagnet de-energized elect

electromagnet energized



P = infeed

A = working line

R = return

1 electromagnet

2 pressure spring

3 spacer pin

4 valve ball

5 valve seat

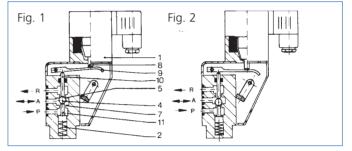
6 valve ball

7 valve seat

8 solenoid plunger

9 lever

10 + 11 pushrod



P = infeed

A = working line

R = return

1 electromagnet2 pressure spring

3 spacer pin

4 valve ball

T valve sent

5 valve seat

dimensional drawing DN 3 and DN 6 DN 3 dimensions shown in brackets

6 valve ball

7 valve seat

8 solenoid plunger

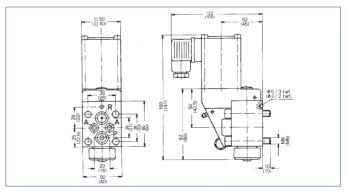
9 lever

10 + 11 pushrod

P = infeed

A =working line

R = return



* Version "positive" = closed de-energzed

** Version " = open de-energized

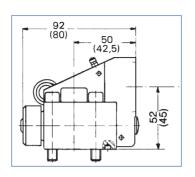
W_	
A.	R
₩ /	R

	NW 3			NW 6		
	Р	R	Α	Р	R	Α
connection bore	Ø3	Ø3	Ø3	Ø3	Ø3	Ø3
Omig			6,07 1,78	12-2,5	12-2,5	8-2

Other valve operating modes NW 3 and NW 6 dimensions in brackets NW 3

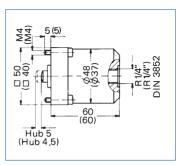


Valve body with console

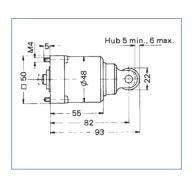


Hydraulic and pneumatic operation

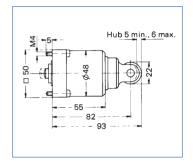
Pressure range:
Pneumatic 2,5-64 bar
Hydraulic 2,5-64 bar
22-320 bar



Mechanical operation



Manual operation



Electro magnetic operation NW3 and NW6, firedamp-proof and explosion-proof

type dE4 (NW3) and dE3 (NW6), protection class acc. to VDE 0170/0171 $\,$

NW3:

(Sch)d/(Ex)d2 G4 certificate No.T5681/BVS

NW6:

(Sch)d/(Ex)d2 G5 certificate No.T5538/BVS

NW3/Pg 16 DIN 22419 available for voltages from 12 - 240 V direct and alternating current.

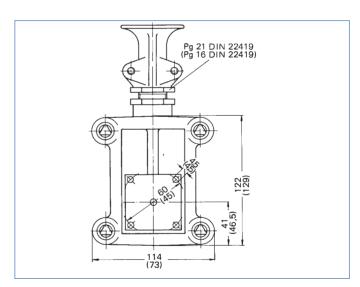
power consumption: up to approx. 20 Watt

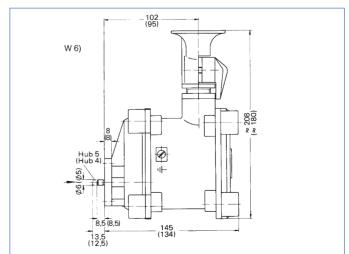
connection cable:

12,5 - 14 mm (A15) NW6/Pg 21 DIN 22419 available for voltages from 24 - 500 V direct and alternating current.

power consumption: up to approx. 32 Watt

connection cable: 15 - 19 mm (A19)





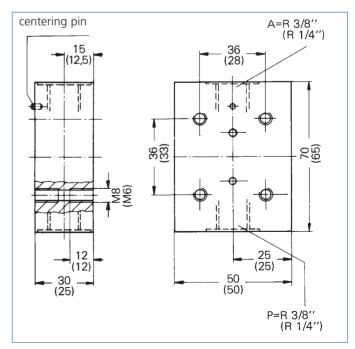
Technical data of actuators NW3



actuator	NW 3							
design type		electro	magnet		hydraulic our pn	roller actuation		
			dE 4	dE 4	Zyl. 31295	Zyl. 31887	mech.	
protection class housing	IP 54 DIN 40050	IP 54 DIN 40050	(Sch)d/(EX)d2G4 VDE 170/0171	(Sch)d/(EX)d2G4 VDE 170/0171				
protection class connection compartment			(Sch)e/(Ex)e VDE 0170/0171 IP 54 DIN 40050	(Sch)e/(Ex)e VDE 0170/0171 IP 54 DIN 40050				
connection typ	plug	plug	terminal	terminal	thread R1/4"	thread R1/4"		
control medium					oil in water emulsion, compressed air and neutral gases	oil in water emulsion,		
medium temperature					- 30° C to + 110° C	- 30° C to + 110° C		
ambient temperature	max. +35°C	max. +35°C	max. +40°C	max. +40°C	max. +80°C	max. +80°C	max. +80°C	
pressure range					2,5-64 bar	25-320 bar		
mounting position	any	any	any	any	any	any	any	
operating voltage*	24 V=	220 V ~	24 V=	220 V ~				
current intensity	0,54 A	0,65 A	0,54 A	0,65 A				
switch-on period	100% ED	100% ED	100% ED	100% ED				
pull-in power	13 W	13 W	13 W	13 W				
hold performance	13 W	13 W	13 W	13 W				
on period (100bar)								
off period								
lifting force	31 N	26 N	31 N	26 N				

^{*} Other voltages possible

Connection plate 2/2 way NW 3 and NW 6 Dimensions in brackets NW 3



Technical data of actuators NW6



actuator	NW 6							
design type		electro	magnet		hydraulic our pn	roller actuation		
			dE 3	dE 3	cyl. 31110	cyl. 31136	mech. 31099	
protection class housing	iP 54 DIN 40050	iP 54 DIN 40050	(Sch)d/(EX)d2G5 VDE 170/0171	(Sch)d/(EX)d2G5 VDE 170/0171				
protection class connection compartment			(Sch)e/(Ex)e VDE 0170/0171 iP 54 DIN 40050	(Sch)e/(Ex)e VDE 0170/0171 iP 54 DIN 40050				
connection typ	plug	plug	terminal	terminal	thread R1/4"	thread R1/4"		
control medium					oil in water emulsion, compressed air and neutral gases	oil in water emulsion,		
medium temperature					- 30° C to + 110° C	- 30° C to + 110° C		
ambient temperature	max. +35°C	max. +35°C	max. +40°C	max. +40°C	max. +80°C	max. +80°C	max. +80°C	
pressure range					2,5-64 bar	25-320 bar		
mounting position	any	any	any	any	any	any	any	
operating voltage*	24 V=	220 V ~	24 V=	220 V ~				
current intensity	1,5 A	0,18 A	1,2 A	0,148 A				
switch-on period	100% ED	100% ED	100% ED	100% ED				
pull-in power	36 W	36 W	13 W	29 W				
hold performance	36 W	36 W	13 W	29 W				
on period (100 bar)	83 ms	73 ms	112 ms	124 ms				
off period	20 ms	113 ms	24 ms	80 ms				
lifting force	93 N	79 N	58 N	54 N				

^{*} Other voltages possible

Connection plate 3/2 way NW 3 and NW 6 Dimensions in brackets NW 3

